

## Simplex Method :-

The Simplex method also called the Simplex technique or the Simplex algorithm is an iterative procedure for solving a linear programming problem in a finite number of steps.

There are three types :-

- \* Simplex method
- \* Big (M) method (or) penalty method.
- \* Two phase method

## Simplex method:

The Simplex algorithm:

For the solution of LPP by simplex algorithm the existence of an initial basic feasible solution is always assumed.

The Steps for the computation of an optimum solution are as follows:

**Step 1:**

check whether the objective function of given LPP is to be maximized or minimized.

If it is to be minimized then we convert it into a problem of maximizing it by using the result

$$\text{Maximize } z = - \text{minimize } (-z)$$

**Step 2:**

check whether all  $b_i$  ( $i=1, 2, \dots, m$ ) are non-negative. If any one of  $b_i$  is negative

then multiply the corresponding inequalities of the constraints by  $-1$ , so as to get all  $b_i$  ( $i=1, 2, \dots, m$ ) non-negative.

**Step 3:**

convert all the inequalities of the constraints into equations by introducing slack and/or surplus variables in the constraints. put the values of these variables equal to zero.

**Step 4:**

obtain an initial basic feasible solution to the problem in the form  $X_B = B^{-1}b$  and put it in the first column of the simplex table.

### Step 5:

Compute the net evaluations  $z_j - c_j$  ( $j=1, 2, \dots, n$ ) by using the relation  $z_j - c_j = C_B \cdot Y_j - c_j$

Examine the sign  $z_j - c_j$

(i) If all  $(z_j - c_j) \geq 0$  then the initial basic feasible solution  $Y_B$  is an optimum basic feasible solution.

(ii) If atleast one  $(z_j - c_j) < 0$ , proceed onto the next step

### Step 6:

If there are more than one negative  $z_j - c_j$ , then choose the most negative of them. Let it be  $z_r - c_r$  for some  $j=r$

(i) If all  $y_{ir} \leq 0$  ( $i=1, 2, \dots, m$ ) then there is an unbounded solution to the given problem.

(ii) If atleast one  $y_{ir} > 0$  ( $i=1, 2, \dots, m$ ) then the corresponding vector  $y_i$  enters the base  $Y_B$ .

### Step 7:

Compute the ratios

$$\left\{ \frac{x_{Bi}}{y_{ir}} \mid y_{ir} > 0, i=1, 2, \dots, m \right\} \text{ and choose}$$

the minimum of them. Let the minimum of the ratios be  $x_{Br} / y_{kr}$ . Then the vector  $y_k$  will leave the base  $Y_B$ . The common element  $y_{kr}$ , which is in the  $k^{\text{th}}$  row and  $r^{\text{th}}$  column is known as the leading element [or pivotal element] of the table.



### Step 8:

Convert the leading element to unity by dividing its row by the leading element itself and all other element in its column to zero by making use of the relations

$$y_{ij}^{\wedge} = y_{ij} - \frac{y_{kj}}{y_{kr}} \cdot y_{ir}, \quad j=1, 2, \dots, m+n, \\ i \neq k$$

and

$$y_{kj}^{\wedge} = \frac{y_{kj}}{y_{kr}} \quad j=0, 1, 2, \dots, n$$

### Step 9:

Go to Step 5 and repeat the computational procedure until either an optimum solution is obtained or there is an indication of an unbounded solution.

1. Use simplex method to solve the following

LPP.  $\text{Max } z = 4x_1 + 10x_2.$

subject to constraints:

$$2x_1 + x_2 \leq 50$$

$$2x_1 + 5x_2 \leq 100$$

$$2x_1 + 3x_2 \leq 90$$

$$x_1, x_2 \geq 0.$$

Soln:

By introducing slack variables  $x_3, x_4, x_5 \geq 0$  respectively.

The given set of constraints are converted into system of equations.

$$2x_1 + x_2 + x_3 = 50$$

$$2x_1 + 5x_2 + x_4 = 100$$

$$2x_1 + 3x_2 + x_5 = 90$$

To obtain an initial basic feasible solution

$$x_3 = 50$$

$$x_4 = 100$$

$$x_5 = 90$$

The general form of objective function is

$$z^* = 4x_1 + 10x_2 + 0x_3 + 0x_4 + 0x_5 \rightarrow \text{Maximize Variable}$$

Co. Eff. of $x_j$	$y_B$	$x_B$	$y_1$	$y_2$	$y_3$	$y_4$	$y_5$	$x_B/y_{ir}$
0	$y_3$	50	2	1	1	0	0	$50/1 = 50$
0	$y_4$	100	2	5	0	1	0	$100/5 = 20$ <small>(Least value)</small>
0	$y_5$	90	2	3	0	0	1	$90/3 = 30$
$z_j - c_j$	20	0	-4	-10	0	0	0	

5 is pivotal element

$y_4$  is leaving variables

$y_2$  is entering variables.

Cost of

$c_B$	$y_B$	$x_B$	$y_1$	$y_2$	$y_3$	$y_4$	$y_5$	$x_B/y_{ir}$
0	$y_3$	<del>50</del> 30	8/5	0	1/5	-1/5	0	
10	$y_2$	20	2/5	1	0	1/5	0	
0	$y_5$	30	4/5	0	0	-3/5	1	
$z_j - c_j$	20	200	0	0	0	0	0	

Old  $R_1 - 1$  (New  $R_2$ )

$$50 - 1(20) = 30$$

$$2 - 1(2/5) = 8/5$$

$$1 - 1(1) = 0$$

$$1 - 1(0) = 1$$

$$0 - 1(1/5) = -1/5$$

$$0 - 1(0) = 0$$

Old  $R_3 - 3$  (New  $R_3$ )

$$90 - 3(20) = 30$$

$$2 - 3(2/5) = 4/5$$

$$3 - 3(1) = 0$$

$$0 - 3(0) = 0$$

$$0 - 3(1/5) = -3/5$$

$$1 - 3(0) = 1$$

Since all  $Z_j - C_j \geq 0$  an optimum basic feasible solution has been reached. Hence an optimum basic feasible solution to the given LPP is

$$x_1 = 0$$

$$x_2 = 20$$

$$\text{maximize } z = 800$$

**Check:**

$$2x_1 + x_2 + x_3 = 50$$

$$0 + 20 + 30 = 50$$

$$2x_1 + 5x_2 + x_4 = 100$$

$$0 + 100 + 0 = 100$$

$$2x_1 + 3x_2 + x_5 = 90$$

$$0 + 60 + 30 = 90$$



## Big (M) Method: (Method of Penalties).

The Big (M) method is an alternative method of solving a linear programming problem involving artificial variables. In this method we assign a very high penalty (say M) to the artificial variable in the objective function.

The iterative procedure of the algorithm:

Step 1:

Write the given LPP into its standard form and check whether there exists a starting basic feasible solution.

a) If there is a ready starting basic feasible solution move on to step 4.

b) If there does not exist a ready starting basic feasible solution move on to step 2.

Step 2:

Add artificial variables to the left side of each equation that has no obvious starting basic variables. Assign a very high penalty (say M) to these variables in the objective function.

Step 3:

Apply simplex method to the modified LPP following cases may arise at the last iteration.

a) Affect one artificial variable is present in the basic with zero value. In such a case the current optimum basic feasible solution is degenerated.

b) Atleast one artificial variable is present in the basic with a positive value. In such a case the given LPP does not possess an optimum basic feasible solution. The given problem is said to have a pseudo-optimum basic feasible solution.



$$\text{max } (z) = 6x_1 + 4x_2$$

Subject to constraints

$$2x_1 + 3x_2 \leq 30$$

$$3x_1 + 2x_2 \leq 24$$

$$x_1 + x_2 \geq 3$$

$$x_1, x_2 \geq 0$$

Soln:

Introducing slack and surplus variables

with an artificial variable  $x_3, x_4, x_5, x_6$

in the constraints of given LPP.

The given set of constraints are converted into system of equations

$$2x_1 + 3x_2 + x_3 = 30$$

$$3x_1 + 2x_2 + x_4 = 24$$

$$x_1 + x_2 - x_5 + x_6 = 3$$

The general form of objective function is

$$z^* = 6x_1 + 4x_2 + 0x_3 + 0x_4 + 0x_5 - Mx_6$$

CB	YB	XB	6	4	0	0	0	-M	$x_i/b_{ij}$
0	$y_3$	30	2	3	1	0	0	0	15
0	$y_4$	24	3	2	0	1	0	0	8
-M	$y_6$	3	1	1	0	0	-1	1	3
$Z_j - C_j$	20	-M	-m-6	-m-4	0	0	0	-M	

1 is pivotal element

$y_6$  is leaving variable

$y_1$  is entering variable

CB	YB	XB	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$\frac{RHS}{y_{ij}}$
0	$x_3$	30	0	1	1	0	3	10
0	$x_4$	15	0	-1	0	1	3	5
6	$x_1$	3	1	1	0	0	-1	-3
$Z_j - C_j \geq 0$		18	0	3	0	0	-6	

Old  $R_1 - 2(\text{New } R_3)$

$$30 - 2(3) = 24$$

$$2 - 2(1) = 0$$

$$3 - 2(1) = 1$$

$$1 - 2(0) = 1$$

$$0 - 2(0) = 0$$

$$0 - 2(-1) = 2$$

Old  $R_2 - 3(\text{New } R_3)$

$$15 - 3(3) = 6$$

$$3 - 3(1) = 0$$

$$2 - 3(1) = -1$$

$$0 - 3(0) = 0$$

$$1 - 3(0) = 1$$

$$0 - 3(-1) = 3$$

3 is pivotal element

$x_4$  is leaving variable

$x_5$  is entering variable.

CB	YB	XB	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$\frac{RHS}{y_{ij}}$
0	$x_3$	14	0	$\frac{5}{3}$	0	$\frac{2}{3}$	0	
0	$x_5$	5	0	$-\frac{1}{3}$	0	$\frac{1}{3}$	1	
6	$x_1$	8	1	$\frac{2}{3}$	0	$\frac{1}{3}$	0	
$Z_j - C_j \geq 0$		48	0	0	0	0	0	

Since all  $Z_j - C_j \geq 0$  an optimum basic feasible solution has been reached.

Hence an optimum basic feasible solution to the given LPP is

$$x_1 = 8 \quad x_4 = 0$$

$$x_2 = 0 \quad x_5 = 5$$

$$x_3 = 14$$

$$\max(Z) = 48$$