

**POSITIVE DEFINITION:**

We suppose that  $E(x,y)$  is cts and has cts 1<sup>st</sup> partial derivatives in some region containing origin. We say that the function  $E(x,y)$  is +ve definite if (i)  $E(0,0) = 0$  (ii)  $E(x,y) > 0$  for  $(x,y) \neq (0,0)$ .

**NEGATIVE DEFINITE:**

We suppose that  $E(x,y)$  is cts and has cts 1<sup>st</sup> order partial derivatives in some region containing  $(0,0)$ . We say that the function  $E(x,y)$  is defined by

- (i)  $E(0,0) = 0$
- (ii)  $E(x,y) < 0$  for  $(x,y) \neq (0,0)$

**POSITIVE SEMI-DEFINITE:**

We suppose that  $E(x,y)$  is cts and possessing cts partial derivative on some region containing  $(0,0)$ . We say that the function  $E(x,y)$  in -ve semi definite if

$$E(x,y) \leq 0 \text{ for } (x,y) \neq (0,0)$$

**ILLUSTRATION:**

consider  $E(x,y) = ax^{2m} + by^{2n}$  where  $a, b$  are +ve constant &  $m, n$  are +ve integers,

P.T  $E$  is +ve definite

soln:

$$\text{Given } E(x,y) = ax^{2m} + by^{2n}$$

To P.T  $E$  is +ve definite if it is suffices to prove

(i)  $E(0,0) = 0$  (ii)  $E(x,y) > 0$  for  $(x,y) \neq (0,0)$

Putting  $x=0$  &  $y=0$  in ①

$E(0,0) = 0$  for  $x \neq 0, y \neq 0$

$E(x,y) = 0, ax^{2m} + by^{2m} > 0$

$\therefore a > 0, b > 0, x^{2m} > 0, y^{2m} > 0$

$E(x,y)$  is +ve definite

Remark:

$E(x,y)$  is -ve definite  $\Leftrightarrow -E(x,y)$  is +ve definite

ILLUSTRATION: Let  $E(x,y) = ax^{2m} + by^{2n}$ ,  $E(x,y)$  is -ve definite

Proof:

GIVEN  $E(x,y) = ax^{2m} + by^{2n}$

TO PROVE  $E(x,y)$  is -ve definite

i.e.,  $E(x,y) < 0$  for  $(x,y) \neq (0,0)$

Put  $x \neq 0, y \neq 0$  in ① we get

$E(x,y) = ax^{2m} + by^{2n} < 0$

$\therefore a < 0, b < 0$

$E(x,y) < 0$

$\therefore E(x,y)$  is -ve definite

Remark:

Then function  $x^{2m}, y^{2n}$  &  $(x,y)^{2m}$  aren't +ve definite but are +ve semi-definite

LIAPUNOV'S FUNCTION:

Let  $E(x,y)$  be function

(i)  $E(0,0) = 0$ ; (ii)  $E(x,y) > 0$  for  $(x,y) \neq (0,0)$

i.e.,  $E(x,y)$  is a +ve function we say that  $E(x,y)$

is a Liapunov's function.

If  $\frac{dE}{dt} = \frac{dE}{dx} \cdot F + \frac{dE}{dy} \cdot G$  is -ve semi-definite

$\frac{dE}{dx} \cdot F + \frac{dE}{dy} \cdot G < 0$  for  $(x,y) \neq (0,0)$

$\therefore \frac{dE}{dt} < 0$ ,  $E$  is decreasing along the path of ①

near the origin.

THEOREM: LIAPUNOV'S THEOREM:

If  $f$  is a Liapunov's function,  $E(x, y)$  for the system  $\frac{dx}{dt} = F(x, y)$ ,  $\frac{dy}{dt} = G(x, y)$

then the critical pt  $(0, 0)$  is stable function more if it this function has the  $\frac{\partial E}{\partial x} F + \frac{\partial E}{\partial y} G$  is -ve definite. then the critical pt  $(0, 0)$  is asymptotically stable.

Proof:

Let  $c_1$  be the circle of radius  $R > 0$  when  $R$  is a +ve quantity.

$c$  is connected on the origin

We also assume that  $c_1$  is small enough to lie entirely in the domain of the definition of the function  $E$ .

since  $E(x, y)$  is constant & +ve definite. It has a +ve minimum 'm' on  $c_1$ .  $E(x, y)$  is a constant at the origin & vanish whenever  $(x, y)$  is inside the circle  $c_2$  of radius:

Now let  $c = \{x(t)\}$  be any path which is inside  $c_2$  for  $t = t_0$

$$\frac{dE}{dt} = \frac{dE}{dx} \cdot F + \frac{dE}{dy} \cdot G \text{ is a +ve semi definite}$$

$$\therefore \frac{dE}{dt} < 0$$

$E(t) \leq E(t_0) < m$  for  $t < t_0$ . It follows that the path  $c$  can never reach the  $c_1$  for any  $t > t_0$ .

Case (ii)

Hence the critical path  $(0, 0)$  stable. To

Prove 2<sup>nd</sup> proof of the theorem.

It sufficient to show that  $\frac{dE}{dt}$  is a -ve semi definite.

$$\frac{dE}{dt} = \frac{dE}{dx} \cdot \dot{x} + \frac{dE}{dy} \cdot \dot{y}$$

critical path pt (0,0) is -ve semi definite.

$$\frac{dE}{dt} \leq 0$$

It follows that  $E(t)$  is decreasing function.

$E(t) \rightarrow 0$  [  $\because E(x,y)$  is +ve definite the path  $c$  approaches then critical pt (0,0) ]

In other word  $E(t)$  has bounded below by zero. we conclude that,

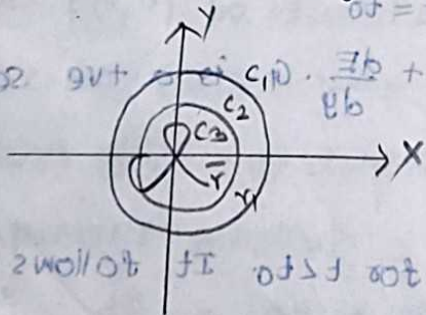
$E(t)$  approaches some  $L \geq 0$  as  $t \rightarrow \infty$ .

TO PROVE :  $E(t) \rightarrow 0$ , we need to prove  $L=0$  we assume that  $L > 0$  and arrive at a contradiction

We choose number  $\bar{r} < r$ . The property then

$E(x,y) < L$  whenever  $(x,y)$  is inside circle  $c$  with radius  $\bar{r}$ .

since  $\frac{dE}{dt}$  is +ve & -ve definite it has a -ve maximum  $(-K)$  in the ring consisting of the circles  $c_1$  &  $c_2$  the origin b/w them



$E(t) \leq E(t_0) + \int_{t_0}^t \frac{dE}{dt} dt$  It follows that the path

The ring contains the entire path  $c$  for  $t \geq t_0$ , so that the eqn

$$E(t) = E(t_0) + \int_{t_0}^t \frac{dE}{dt} dt$$

$$E(t) = E(t_0) + \int_{t_0}^t dE$$

$$E(t) = E(t_0) - K + E(t) - E(t_0)$$

$$\leq E(t_0) - K(t - t_0) \quad \forall t \geq t_0$$

$$E(t) \leq E(t_0) - K(t - t_0)$$

ie in  $t \rightarrow \infty$  the R.H.S of (1) approaches  $-\infty$

$$E(t) \rightarrow -\infty \text{ as } t \rightarrow \infty$$

which is the contradiction on fact that  $E(x,y) \geq 0$ ;

$L=0$

Hence the theorem.

**THEOREM:  $\Sigma K$ :**

consider the eqn of motion of mass 'm' attached to spring,

$$m \frac{d^2 x}{dt^2} + c \frac{dx}{dt} + kx = 0$$

Here  $c \geq 0$  is a constant representing the viscosity of the medium through which the mass moves &  $k > 0$  is the spring constant.

**Proof:**

The Autonomous system equivalent to eqn (1)

$$\frac{dx}{dt} = y, \quad \left( \frac{dy}{dt} \right) = -\frac{kx}{m} - \frac{cy}{m}$$

$$\text{(1)} \Rightarrow m \frac{dy}{dt} + cy + kx = 0$$

$$\frac{m dy}{dt} = -kx - cy$$

$$\frac{dy}{dt} = -\frac{k}{m} x - \frac{c}{m} y$$

Hence the autonomous system for (1) is

$$\frac{dx}{dt} = y, \quad \frac{dy}{dt} = -\frac{k}{m} x - \frac{c}{m} y$$

the only critical pt of (1) is (0,0)

The kinetic Energy of the mass is  $\frac{1}{2} m y^2$