# **UNIT - II**

## **Tree - Terminology**

In linear data structure data is organized in sequential order and in nonlinear data structure data is organized in random order. A tree is a very popular non-linear data structure used in a wide range of applications. A tree data structure can be defined as follows...

# **Tree is a non-linear data structure which organizes data in hierarchical structure and this is a recursive definition.**

A tree data structure can also be defined as follows...

# **Tree data structure is a collection of data (Node) which is organized in hierarchical structure recursively**

In tree data structure, every individual element is called as **Node**. Node in a tree data structure stores the actual data of that particular element and link to next element in hierarchical structure.

In a tree data structure, if we have **N** number of nodes then we can have a maximum of **N-1** number of links.

**Definition** 

A tree is finite set of one or more nodes such that

- (i) There is a specially designated node called the root
- (ii) The remaining nodes are partitioned inti  $n \geq 0$  disjoint sets  $T_1, \ldots, T_n$  where each of these sets is a tree.  $T_1$ ,....,  $T_n$  are called the subtrees of the tree.

## **Example**



## **Terminology**

In a tree data structure, we use the following terminology...

## **1. Root**

In a tree data structure, the first node is called as **Root Node**. Every tree must have a root node. We can say that the root node is the origin of the tree data structure. In any tree, there must be only one root node. We never have multiple root nodes in a tree.



## **2. Edge**

In a tree data structure, the connecting link between any two nodes is called as **EDGE**. In a tree with '**N**' number of nodes there will be a maximum of '**N-1**' number of edges.



### **3. Parent**

In a tree data structure, the node which is a predecessor of any node is called as **PARENT NODE**. In simple words, the node which has a branch from it to any other node is called a parent node. Parent node can also be defined as "**The node which has child / children**".



#### **4. Child**

In a tree data structure, the node which is descendant of any node is called as **CHILD Node**. In simple words, the node which has a link from its parent node is called as child node. In a tree, any parent node can have any number of child nodes. In a tree, all the nodes except root are child nodes.



## **5. Siblings**

In a tree data structure, nodes which belong to same Parent are called as **SIBLINGS**. In simple words, the nodes with the same parent are called Sibling nodes.



## **6. Leaf**

In a tree data structure, the node which does not have a child is called as **LEAF Node**. In simple words, a leaf is a node with no child.

In a tree data structure, the leaf nodes are also called as **External Nodes**. External node is also a node with no child. In a tree, leaf node is also called as '**Terminal**' node.



## **7. Internal Nodes**

In a tree data structure, the node which has atleast one child is called as **INTERNAL Node**. In simple words, an internal node is a node with atleast one child.

In a tree data structure, nodes other than leaf nodes are called as **Internal Nodes**. **The root node is also said to be Internal Node** if the tree has more than one node. Internal nodes are also called as '**Non-Terminal**' nodes.



## **8. Degree**

In a tree data structure, the total number of children of a node is called as **DEGREE** of that Node. In simple words, the Degree of a node is total number of children it has. The highest degree of a node among all the nodes in a tree is called as '**Degree of Tree**'



### **9. Level**

In a tree data structure, the root node is said to be at Level 0 and the children of root node are at Level 1 and the children of the nodes which are at Level 1 will be at Level 2 and so on... In simple words, in a tree each step from top to bottom is called as a Level and the Level count starts with '0' and incremented by one at each level (Step).



## **10. Height**

In a tree data structure, the total number of edges from leaf node to a particular node in the longest path is called as **HEIGHT** of that Node. In a tree, height of the root node is said to be **height of the tree**. In a tree, **height of all leaf nodes is '0'.**



#### **11. Depth**

In a tree data structure, the total number of egdes from root node to a particular node is called as **DEPTH** of that Node. In a tree, the total number of edges from root node to a leaf node in the longest path is said to be **Depth of the tree**. In simple words, the highest depth of any leaf node in a tree is said to be depth of that tree. In a tree, **depth of the root node is '0'.**



#### **12. Path**

In a tree data structure, the sequence of Nodes and Edges from one node to another node is called as **PATH** between that two Nodes. **Length of a Path** is total number of nodes in that path. In below example **the path A - B - E - J has length 4**.



## **13. Sub Tree**

In a tree data structure, each child from a node forms a subtree recursively. Every child node will form a subtree on its parent node.



# **Tree Representations**

A tree data structure can be represented in two methods. Those methods are as follows...

## **1. List Representation**

# **2. Left Child - Right Sibling Representation**

Consider the following tree...



## **1. List Representation**

In this representation, we use two types of nodes one for representing the node with data called 'data node' and another for representing only references called 'reference node'. We start with a 'data node' from the root node in the tree. Then it is linked to an internal node through a 'reference node' which is further linked to any other node directly. This process repeats for all the nodes in the tree.

The above example tree can be represented using List representation as



# **2. Left Child - Right Sibling Representation**

In this representation, we use a list with one type of node which consists of three fields namely Data field, Left child reference field and Right sibling reference field. Data field stores the actual value of a node, left reference field stores the address of the left child and right reference field stores the address of the right sibling node. Graphical representation of that node is as follows...



In this representation, every node's data field stores the actual value of that node. If that node has left a child, then left reference field stores the address of that left child node otherwise stores NULL. If that node has the right sibling, then right reference field stores the address of right sibling node otherwise stores NULL.

## **Binary Tree Data structure**

In a normal tree, every node can have any number of children. A binary tree is a special type of tree data structure in which every node can have a **maximum of 2 children**. One is known as a left child and the other is known as right child.

**A tree in which every node can have a maximum of two children is called Binary Tree.**

In a binary tree, every node can have either 0 children or 1 child or 2 children but not more than 2 children.

#### **Example**



There are different types of binary trees and they are...

# **1. Strictly Binary Tree**

In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none. That means every internal node must have exactly two children. A strictly Binary Tree can be defined as follows...

# **A binary tree in which every node has either two or zero number of children is called Strictly Binary Tree**

Strictly binary tree is also called as **Full Binary Tree** or **Proper Binary Tree** or **2-Tree**



Strictly binary tree data structure is used to represent mathematical expressions. *Example*



# **2. Complete Binary Tree**

In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none and in complete binary tree all the nodes must have exactly two children and at every level of complete binary tree there must be  $2^{level}$  number of nodes. For example at level 2 there must be  $2^2 = 4$  nodes and at level 3 there must be  $2^3 = 8$  nodes.

**A binary tree in which every internal node has exactly two children and all leaf nodes are at same level is called Complete Binary Tree.**

Complete binary tree is also called as **Perfect Binary Tree**



# **3. Extended Binary Tree**

A binary tree can be converted into Full Binary tree by adding dummy nodes to existing nodes wherever required.



In above figure, a normal binary tree is converted into full binary tree by adding dummy nodes (In pink colour).

# **Binary Tree Representations**

A binary tree data structure is represented using two methods. Those methods are as follows...

- **1. Array Representation**
- **2. Linked List Representation**

Consider the following binary tree...



# **1. Array Representation of Binary Tree**

In array representation of a binary tree, we use one-dimensional array (1- D Array) to represent a binary tree.

Consider the above example of a binary tree and it is represented as follows...

$$
A | B | C | D | F | G | H | I | J | - | - | - | K | - | - | - | - | - | - | - | - | - | - |
$$

To represent a binary tree of depth **'n'** using array representation, we need one dimensional array with a maximum size of **2n + 1**.

## *2. Linked List Representation of Binary Tree*

We use a double linked list to represent a binary tree. In a double linked list, every node consists of three fields. First field for storing left child address, second for storing actual data and third for storing right child address. In this linked list representation, a node has the following structure...



The above example of the binary tree represented using Linked list representation is shown as follows...



## **Binary Tree Traversal**

Traversal is a process to visit all the nodes of a tree and may print their values too. Because, all nodes are connected via edges (links) we always start from the root (head) node. That is, we cannot randomly access a node in a tree. There are three ways which we use to traverse a tree −

- In-order Traversal
- Pre-order Traversal
- Post-order Traversal

# *In-order Traversal*

In this traversal method, the left subtree is visited first, then the root and later the right sub-tree. We should always remember that every node may represent a subtree itself.

If a binary tree is traversed **in-order**, the output will produce sorted key values in an ascending order.



We start from **A**, and following in-order traversal, we move to its left subtree **B**. **B** is also traversed in-order. The process goes on until all the nodes are visited. The output of inorder traversal of this tree will be −

$$
D \to B \to E \to A \to F \to C \to G
$$

Algorithm

**Procedure** INORDER (T)

**If**  $T \neq 0$  **then** 

```
[ call INORDER (LCHILD(T))
```
**print**(DATA(T))

**call** (INORDER(RCHILD(T))]

**end** INORDER

**In-Order (Binary only)**

**To visit a node:**

Recursively visit left child.

- Perform an action
- Recursively visit right child.

# **Pre-order Traversal**

In this traversal method, the root node is visited first, then the left subtree and finally the right subtree.



We start from **A**, and following pre-order traversal, we first visit **A** itself and then move to its left subtree **B**. **B** is also traversed pre-order. The process goes on until all the nodes are visited. The output of pre-order traversal of this tree will  $be -$ 

 $A \rightarrow B \rightarrow D \rightarrow E \rightarrow C \rightarrow F \rightarrow G$ 

**Algorithm** 

**Procedure** PREORDER (T)

**If**  $T \neq 0$  **then** 

[ **print**(DATA(T))

 **call** PREORDER (LCHILD(T))

**call** (PREORDER (RCHILD(T))]

**end** PREORDER

# **Post-order Traversal**

In this traversal method, the root node is visited last, hence the name. First we traverse the left subtree, then the right subtree and finally the root node.



We start from **A**, and following Post-order traversal, we first visit the left subtree **B**. **B** is also traversed post-order. The process goes on until all the nodes are visited. The output of post-order traversal of this tree will be −

 $D \to E \to B \to F \to G \to C \to A$ 

Algorithm

**Procedure** POSTORDER (T)

**If**  $T \neq 0$  **then** 

[ **call** POSTORDER(LCHILD(T))

**call** POSTORDER (RCHILD(T))]

 **print**(DATA(T))

**end** POSTORDER



## **Threaded Binary Tree**

A binary tree can be represented using array representation or linked list representation. When a binary tree is represented using linked list representation, the reference part of the node which doesn't have a child is filled with a NULL pointer. In any binary tree linked list representation, there is a number of NULL pointers than actual pointers. Generally, in any binary tree linked list representation, if there are **2N** number of reference fields, then **N+1** number of reference fields are filled with NULL ( **N+1 are NULL out of 2N**). This NULL pointer does not play any role except indicating that there is no link (no child).

A. J. Perlis and C. Thornton have proposed new binary tree called "*Threaded Binary Tree*", which makes use of NULL pointers to improve its traversal process. In a threaded binary tree, NULL pointers are replaced by references of other nodes in the tree. These extra references are called as *threads*.

**Threaded Binary Tree is also a binary tree in which all left child pointers that are NULL (in Linked list representation) points to its in-order predecessor, and all right**  **child pointers that are NULL (in Linked list representation) points to its in-order successor.**

If there is no in-order predecessor or in-order successor, then it points to the root node.

Consider the following binary tree...



To convert the above example binary tree into a threaded binary tree, first find the in-order traversal of that tree...

#### **In-order traversal of above binary tree...**

# **H - D - I - B - E - A - F - J - C - G**

When we represent the above binary tree using linked list representation, nodes **H**, **I**, **E, F, J** and **G** left child pointers are NULL. This NULL is replaced by address of its in-order predecessor respectively (I to D, E to B, F to A, J to F and G to C), but here the node H does not have its in-order predecessor, so it points to the root node A. And nodes **H, I, E, J** and **G** right child pointers are NULL. These NULL pointers are replaced by address of its in-order successor respectively (H to D, I to B, E to A, and J to C), but here the node G does not have its in-order successor, so it points to the root node A.

Above example binary tree is converted into threaded binary tree as follows.



In the above figure, threads are indicated with dotted links.